

SLIDING MODE CONTROL OF SMPS

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ABSTRACT

Digital control technique is a technique for high frequency switching mode power supply (SMPS). The regulation requirement for high frequency integrated DC-DC switching mode power supply becomes more demanding in industry and portable Communication systems at very high frequency beyond 10 Mega Hertz range. Analysis and experimental study of buck converter and the boost converter is presented to achieve desired output voltage. The SMPS are emerging in terms of higher dynamic response performances, less output ripple, smaller size and weight. The sliding mode controller is associated with a digital pulse width modulation (DPWM) block instead of conventional PWM to operate at high switching frequency. Sliding mode control (SMC) can reduce the voltage ripple of SMPS. Sliding mode controller will be used by means of analog to digital conversion (ADC) and Digital pulse width modulation (DPWM).

Keywords-Analog to Digital converter(ADC);Sliding mode control; Digital pulse width modulation(DPWM)

1. INTRODUCTION

Switching mode power supplies provide high efficiency, easy integration small weight and dimension. SMPS used in the portable personal communication system, cell phones, telephones, MP3 players and the other PDA products, have grown explosively in recent years. They are also used in a various applications including computer systems, wireless communication systems, medical instrumentations, motor drives, lighting and consumer electronics. Especially the miniaturization is always a critical consideration for the portable devices. Even now in some portable application, the size of the DC-DC power converters is becoming the primary focus in the overall design. Therefore the technology for high switching frequency operation to reduce size of passive components like inductors and capacitors to obtain miniaturization is urgently needed. Advanced semiconductor integrated technology over the last decade has resulted in a noticeable reduction in the size and weight of electronic components.

2. ANALOG SLIDING MODE CONTROL

SMPS has simplicity and low cost which are operated with analog controllers applications. The analog controlled SMPS operates as follows:The output voltage V_o and the reference voltage V_{ref} are compared, and obtained the error signal $e=V_{ref}-V_o$.

The closed loop operation offers large performance in keeping the output voltage constant and restraining the overshoot during the input voltage or external load changes. The error signal constitutes the input of the controller. The controller can be realized by using an operational amplifier and the network of passive components such as capacitors and resistors. The output of the controller is the control signal u . The pulse width modulator (PWM) is used to transform the control signal u .

The analog components are sensitive to the environment influence, such as temperature, noise, tolerance of fabrication, which results in lack of flexibility, low reliability .It is difficult to apply sophisticated control algorithm with an analog approach implementation. In addition, to meet the size miniaturizations demand the high switching frequency is unavoidable. However in higher switching frequency operation the analog controller signal transmission through the process will suffer from the limitation of band width and the large gain variation. The variability of the integration technology is more critical with higher switching frequency. The sliding surface is

$$S = K (V - V_{ref}) + K \frac{d}{dt}(V - V_{ref}) +$$

$$K \int (V - V_o) dt \quad (1)$$

The control signal of the switched mode power supply with buck converter is

$$= \begin{cases} 1 & (V - V_o) > 0 \\ 0 & (V - V_o) < 0 \end{cases}$$

(2)

The control signal of the boost converter is

$$U = V = -k i + k (V - \beta V_o) + \beta (V - V_o) \quad (3)$$

Where,

$$k = \frac{\alpha}{\alpha} - \frac{\alpha}{\alpha} \quad (4)$$

$$k = LC \frac{\alpha}{\alpha}$$

(5)

3. DIGITAL SLIDING MODE CONTROL

In order to reduce size and improve the system performance, the digital controllers are used. The digital controller consists of three blocks: analog to digital converter (ADC), digital control law and digital PWM (DPWM), and all these blocks should be integrated in one chip. In conventional PWM control schemes, the control signal is compared to the ramp waveform to generate a discrete gate pulse signal. The advantage of PWM based SMC are that it does not need additional hardware circuitries since the switching function is performed by the PWM modulator, which can be implemented inside the digital controller.

However in order to preserve the original sliding mode control laws, the practical implementation of PWM based SMC is little importance, when both current and voltage state variable are involved. The digital controller SMPS operates similarly as the analog controller as follows: The output voltage V_o subtracted from the reference voltage V_{ref} results in the voltage error. The ADC transfers the analog error to discrete in digital signals. During each switching period, the error value is sent to the control law block, where the controller makes algorithm calculation to regulate the output by new digital control duty of PWM ratio. Through the DPWM block, the digital duty value is converted into time analog signal to drive MOSFET switches.

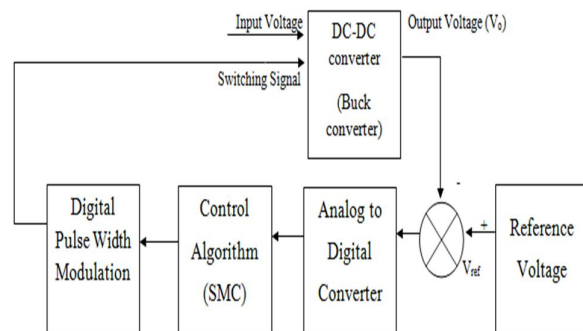


Figure 1. Block diagram of Sliding mode control.

The algorithm of control law can be implemented with internal structure of logic circuits, without any external analog component. Thus the digital controller should be less sensitive to environment than analog counterpart. Also digital control law offers possibility to implement more sophisticated control strategies and other intelligent interface functions that are impractical in analog.

4. SIMULATION CIRCUITS OF CONVENTIONAL METHODS

The simulation circuits of the control techniques are simulated with the help of MATLAB/SIMULINK software.

A. Open loop Buck Converter

Fig.2 shows the circuit diagram of buck converter. It consists of MOSFET, inductance, DC source and load. The external triggering pulse is given to each MOSFET. This converter is used to decrease the output voltage. It converts high voltage DC supply to low voltage DC supply.

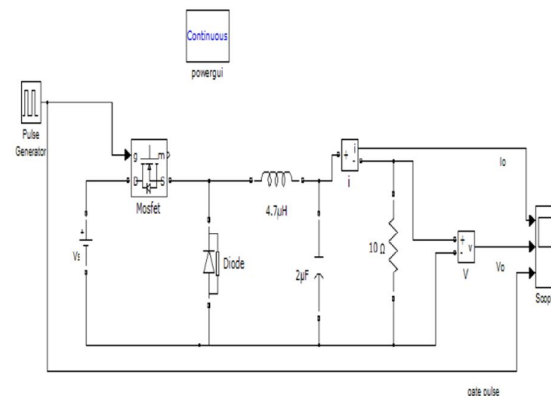


Figure 2. Simulation circuit diagram of open loop buck converter.

B. Closed loop Buck Converter using Pulse Width Modulation Control

The closed loop buck converter with pulse width modulation control is simulated with the output voltage and the reference voltage. These voltages are added. The error signal is produced, which is compared with the external repeating sequence. The compared pulse is given to the MOSFET switch. It controlled the buck converter of switched mode power supply.

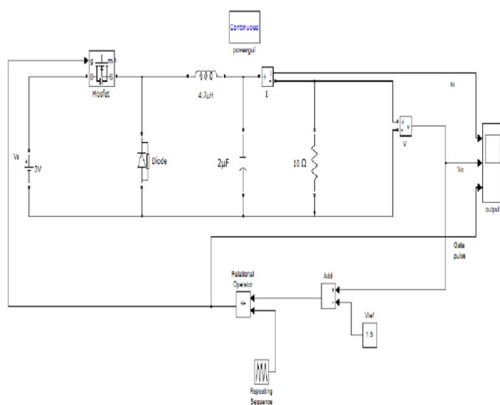


Figure 3. Simulation circuit of closed loop buck converter using pulse width modulation

C. Closed loop buck converter with Sliding Mode Control

The control circuit consists of a linear part; usually for simplicity it is represented with integrator and gain part; usually for simplicity it is represented with integrator and gain part. The second part is the non linear control. The non linear part represented by the hysteresis block could be implemented as the switch off and switch on points, here it is represented with current ripple.

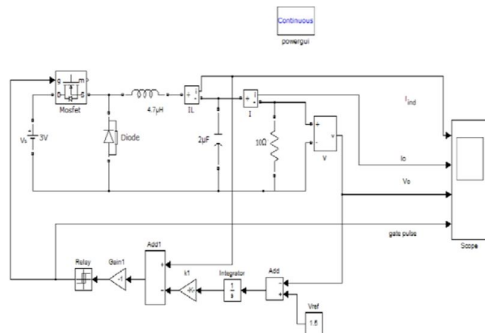


Figure.4 Simulation circuit of closed loop buck converter with Sliding mode control.

D. Open loop boost converter

Fig.5 shows the simulation circuit of open loop boost converter. It consists of MOSFET, inductance, DC source and load. The external triggering pulse is given to each MOSFET. This converter is used to increase the output voltage. It converts low voltage to high voltage. The output voltage is controlled by controlling the firing angle of the MOSFET.

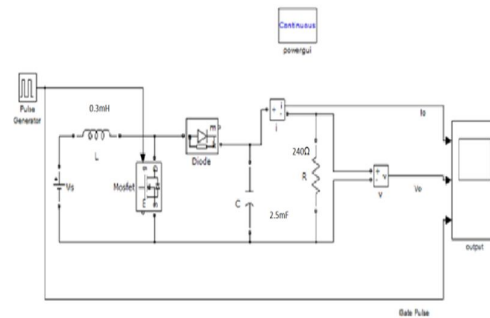


Figure.5 Simulation circuit of open loop boost converter.

E. Closed loop boost converter with Pulse Width Modulation Control

The closed loop boost converter with pulse width modulation control is simulated with the output voltage and the reference voltage. These voltages are added. The error signal is produced, which is compared with the external repeating sequence. The compared pulse is given to the MOSFET switch. It controlled the boost converter of switched mode power supply.

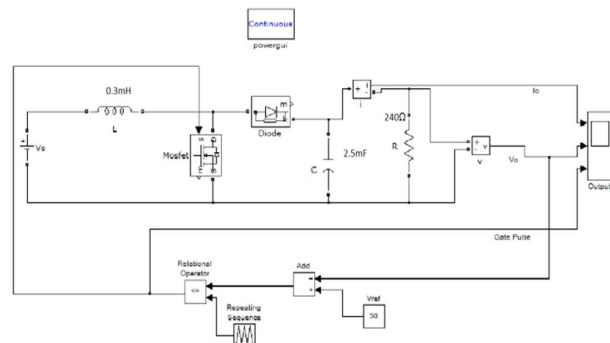


Figure 6. Simulation circuit of closed loop boost converter using pulse width modulation.

F. Closed loop boost converter with Sliding Mode Control

Using control voltage equation, the sliding mode controller for boost converter can be modeled as shown in fig.7. The pulse is generated and triggered the MOSFET.

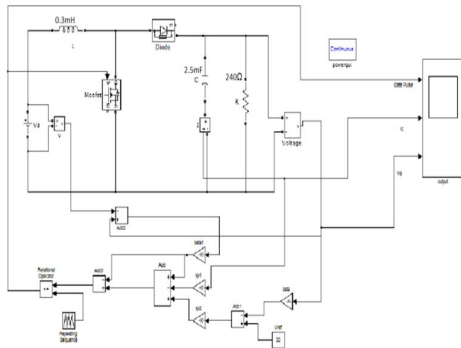


Figure 7. Simulation circuit of boost converter with sliding mode control.

5. SIMULATION CIRCUITS OF PROPOSED METHOD

The simulation circuit of the proposed method is simulated with the help of ORCAD PSpice software.

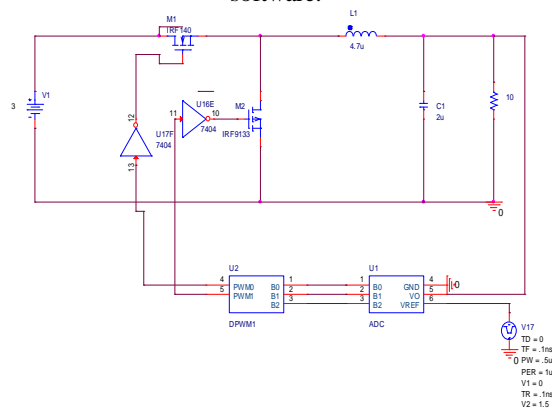


Figure 8. Simulation circuit of Digital sliding mode control

The simulation circuit of the digital sliding mode control of switched mode power supply consists of analog to digital converter (ADC), control and digital pulse width modulation (DPWM). The analog to digital converter is a flash type analog to digital converter. The conversion involves quantization of the input, so it introduces a small amount of error. Instead of doing a single conversion, an ADC often performs the conversion of samples periodically. The result is a sequence of digital values that have converted continuous amplitude and continuous time analog signal to discrete amplitude and discrete time signal. The output voltage of the DC-DC converter and

reference voltage are the input of the analog to digital converter gives three bit output they are B0, B1, B2.

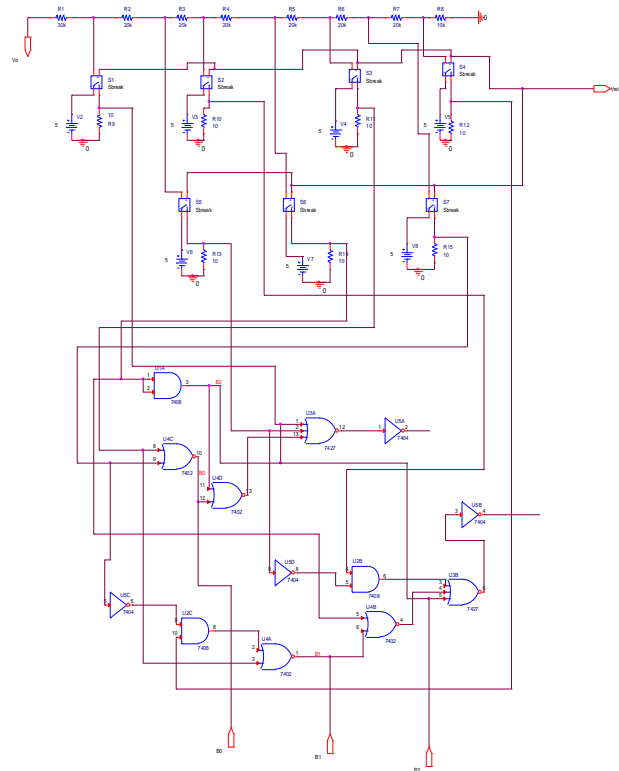


Figure 9. Simulation circuit of analog to digital converter

In classical PWM control schemes, the control signal is compared to the ramp waveform to generate a discrete gate pulse signal. The advantages of the PWM based SMC are that it does not need a additional hardware circuits. A high resolution, high frequency digital pulse width modulator (DPWM) can be constructed using a fast clocked counter and digital comparator. To achieve n bit resolution at the switching frequency F_s takes the digital value d of the duty ratio and produces the pulsating waveform that controls the power MOSFETs in the power converter. The inputs of the ADC are sensed output voltage and the reference voltage and the outputs are 3 bit digital output the ADC having encoder part to converter the 8 bit analog signal to digital signal. The DPWM having digital circuits like flip flops, multiplexers, digital compactors. The switching pulse generated by these digital pulse width modulators. The pulse is given to the switching voltage of the MOSFETs.

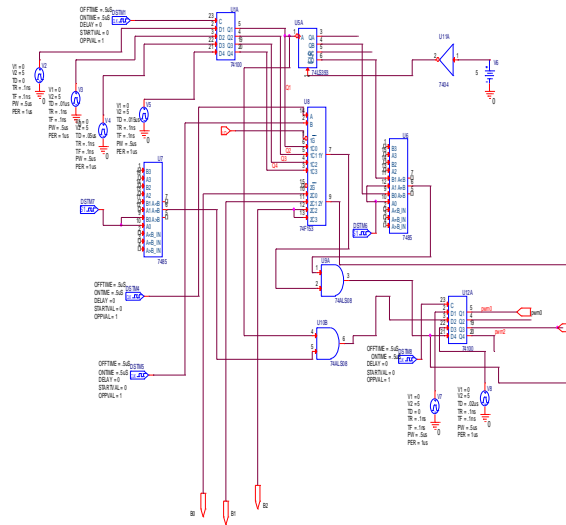


Figure 10..Simulation circuit of digital pulse width modulator.

6. SIMULATION RESULTS

The simulation results of conventional techniques and digital sliding mode control of buck converter shows the result of output voltage and the output current. The simulation results of boost converter control techniques also shown.

A. Open loop buck converter

Fig.11 depicts the input dc source of magnitude 3V. This voltage is fed to the buck converter, reduce the input source voltage into 1.4V.

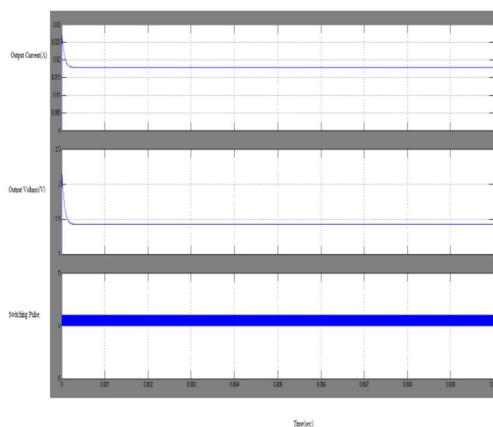


Figure 11.Simulation result of open loop buck converter.

B. Closed loop Buck Converter with Pulse Width Modulation Control

Fig.12 depicts the input dc source of magnitude 3V. This voltage is fed to the buck converter, reduces the input source voltage. The output waveforms of output voltage, output current depends the pulse width in PWM control.

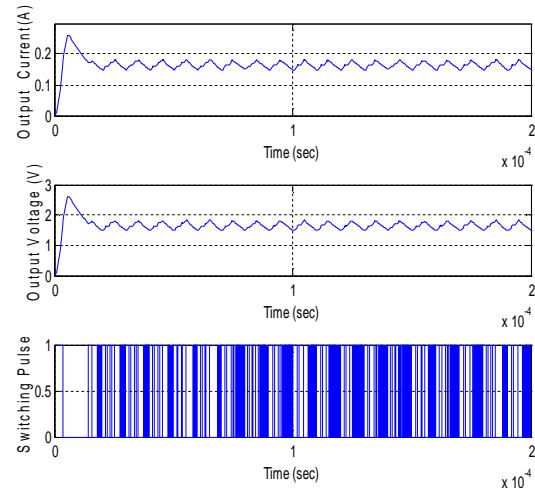


Figure 12.Closed loop buck converter with Pulse width modulation

Fig.13 depicts the input dc source of magnitude 3V. This voltage is fed to the buck converter, which reduce the input source voltage. The ripple of the circuit is 0.3V

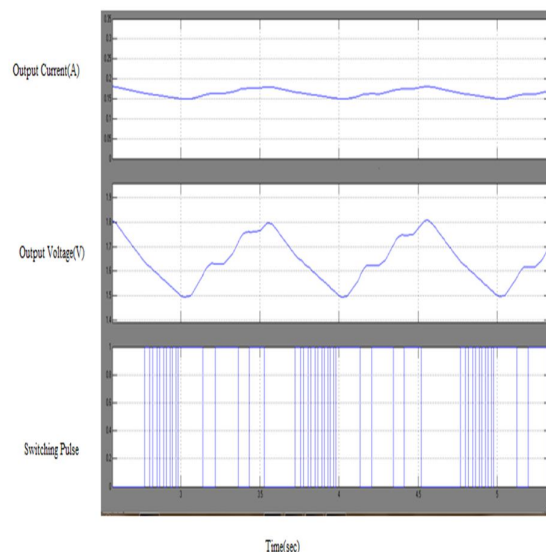


Figure 13.Simulation result of closed loop buck converter with pulse width modulation

C. Closed loop buck converter with Sliding Mode Control

Fig.14 depicts the input dc source of magnitude 3V. This voltage feed to the buck converter, reduce the input source voltage. The overshoot also reduced.

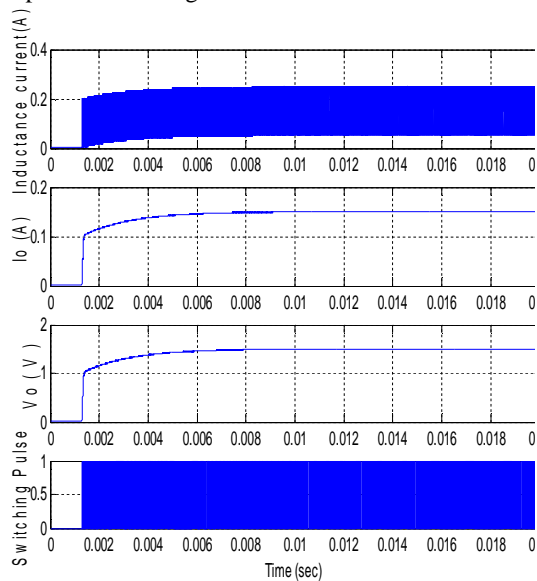


Figure 14.Closed loop buck converter with sliding mode control

Fig.15 depicts the input dc source of magnitude 3V. This voltage feed to the buck converter, which reduce the input source voltage. The ripple voltage is 0.01V

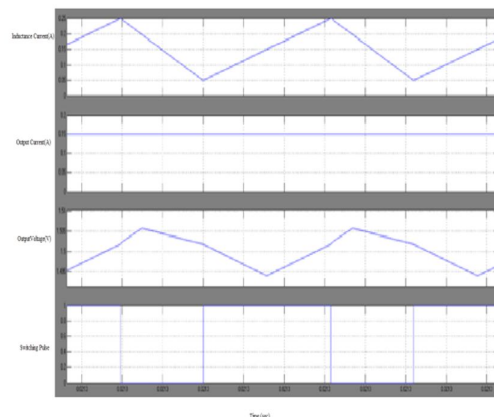


Figure 15.. Simulation result of closed loop buck converter with sliding mode control

D. Open loop boost converter

Fig.16 depicts the input dc source of magnitude 24V. This voltage fed to the boost converter, which increase the input source voltage to 47.15V.

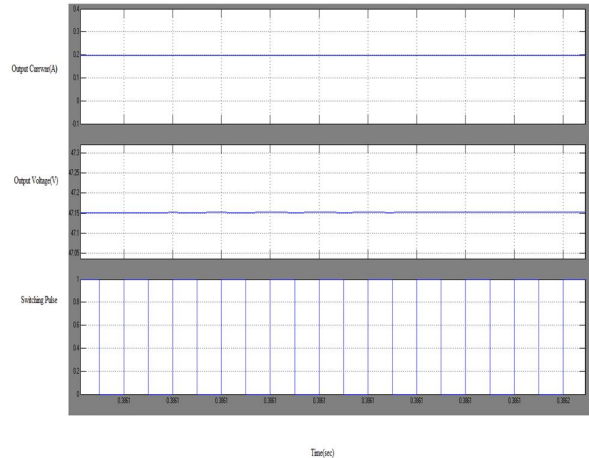


Figure 16. Simulation result of open loop boost converter.

E. Closed loop boost converter with Pulse Width Modulation Control

Fig.17 depicts the input dc source of magnitude 24V. This voltage fed to the boost converter, which increase the input source voltage.

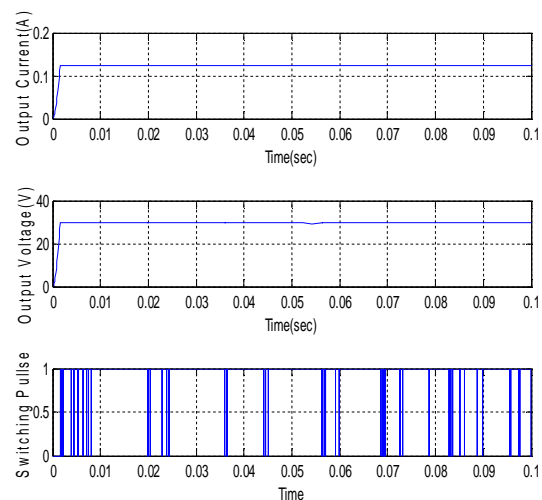


Figure 17.Closed loop boost converter with pulse width modulation.

Fig.18 depicts the input dc source of magnitude 24V. This voltage fed to the boost converter increase

the voltage to 29.8V. The ripple voltage of the boost converter is 0.5V.

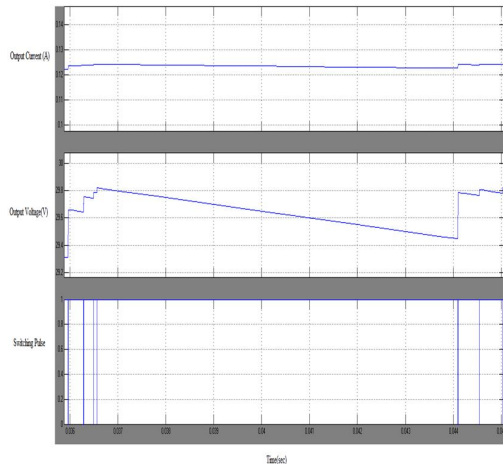


Figure 18.Simulation result of closed loop boost converter with pulse with modulation

F. Closed loop boost converter with Sliding Mode Control

Fig.19 depicts the input dc source of magnitude 24V. This voltage is fed to the boost converter increase the input source voltage. The output waveforms of output voltage, depends the sliding mode

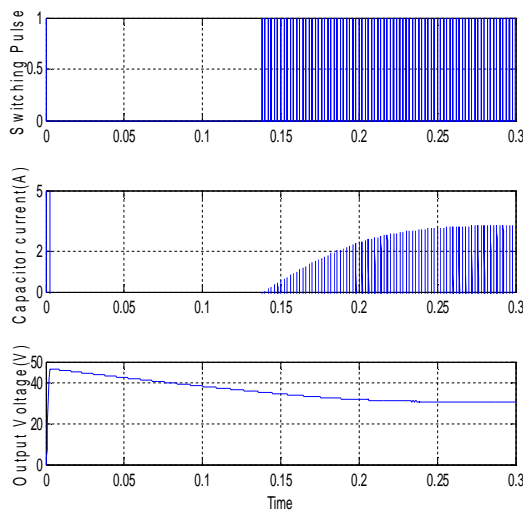


Figure 19. Closed loop boost converter with sliding mode control.

Fig.20 depicts the input dc source of magnitude 24V. This voltage fed to the boost converter. The output voltage increased to 30.4V. The output ripple voltage is 0.1V

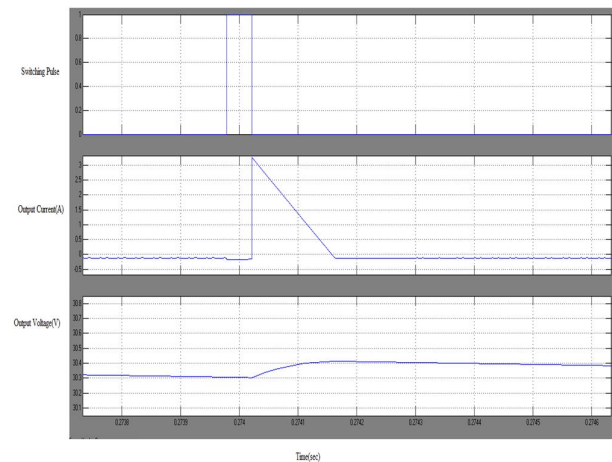


Figure 20.Simulation result of closed loop boost converter with sliding mode control

G. Simulation circuit result of the proposed method:Digital Sliding Mode Control

Fig.21 depicts the input dc source of magnitude 3V. This voltage fed to the buck converter, reduce the input source voltage. The output waveforms of output voltage is reduced to 1.36V with very low ripple voltage 0.2mV.

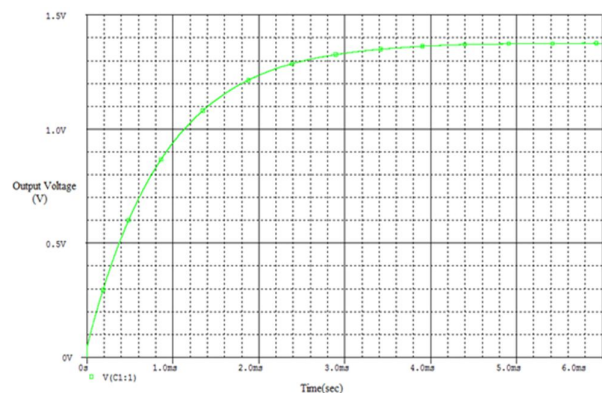


Figure 21.Simulation result of Digital sliding mode control.

7. CONCLUSION

The simulation circuit of sliding mode control and PWM control of SMPS was explained. Simultaneous output voltage, output current and ripple voltage were observed with respect to input.

Table I shows the comparison of output voltage, output current and the ripple voltage of control techniques.

Table.1Output comparison of control techniques

Converter	Control Technique	Input Voltage (V)	Output Current (A)	Output Voltage (V)	Ripple Voltage (V)
Buck Converter	PWM control	3	0.18	1.8	0.3
	Sliding mode control	3	0.15	1.505	0.01
	Digital Sliding mode control	3	0.11	1.36	0.0002
Boost Converter	PWM control	24	0.125	29.5	0.5
	Sliding mode control	24	0.126	30.4	0.1

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